Scalable smoothing with BART

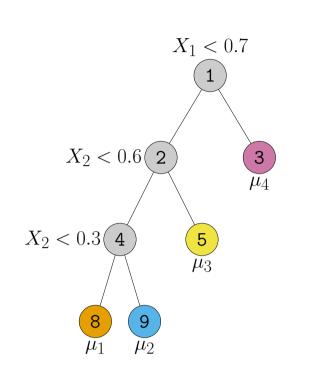
Ryan Yee

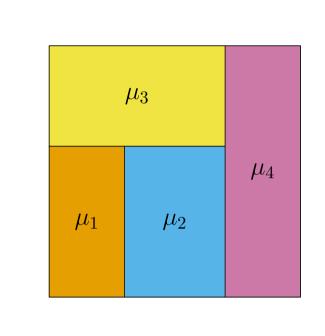
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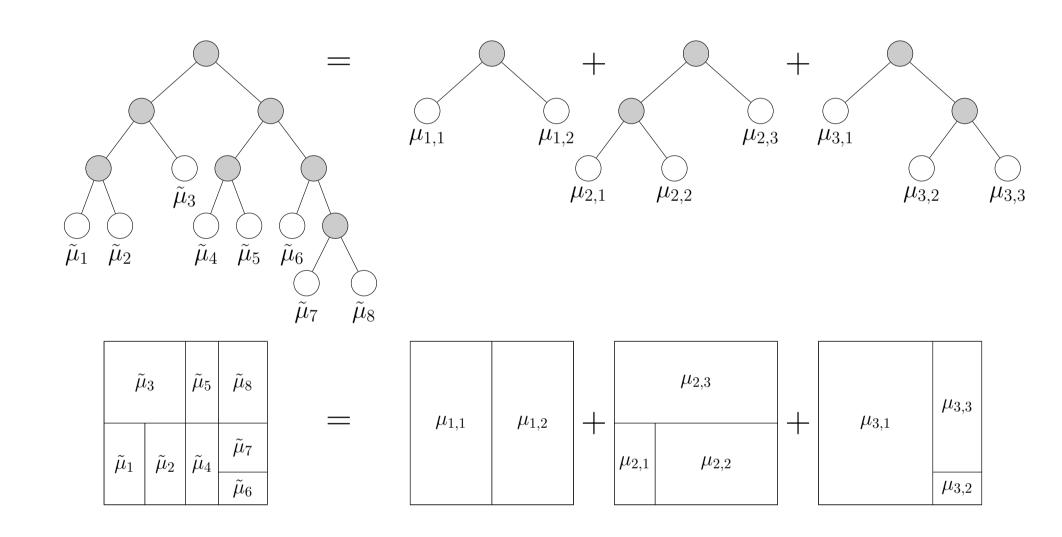
Introduction to BART

- **Problem:** non-parametric regression: $y_n \sim \mathcal{N}\left(f(\mathbf{x}_n), \sigma\right)$
- Main Idea: approximate $f(\mathbf{x})$ with step-function (i.e., tree)

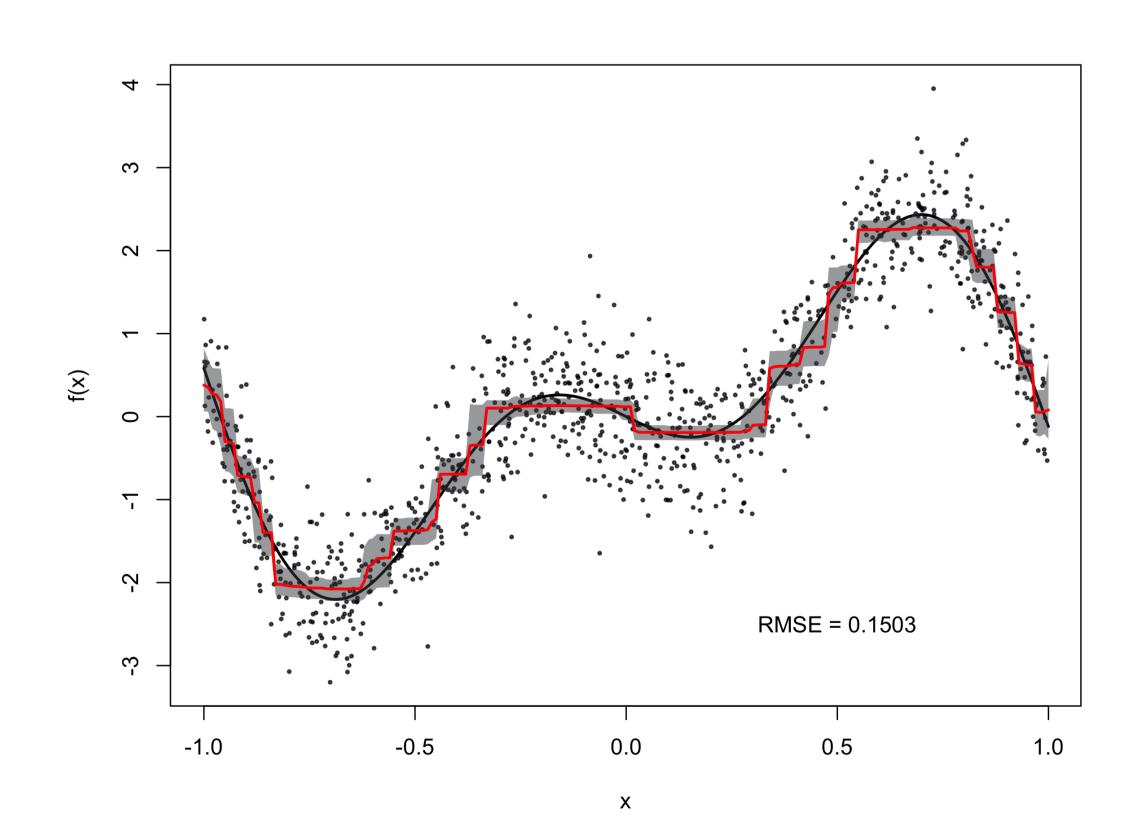




• Insight: express complicated tree as sum of simpler trees



• Result: function estimation with uncertainty quantification



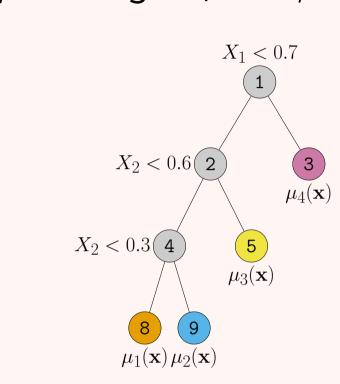
Issue: BART inherently produces non-smooth outputs

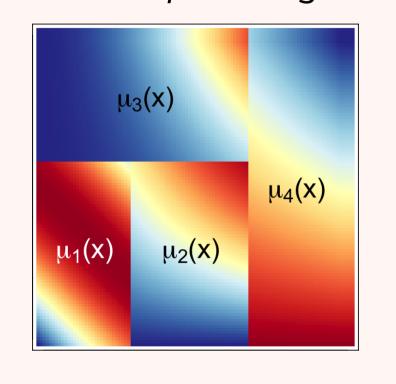
Our Contribution

We introduce BART with functional outputs of the form:

$$\mu(x) = \sum_{d=1}^{D} \beta_d h(\omega_d^{\mathsf{T}} x + b_d)$$

where h is a fixed activation function, $\Theta = (\{\omega_d, b_d\})$ collects all input weights, and $\beta = (\{\beta_d\})$ is a vector of output weights.





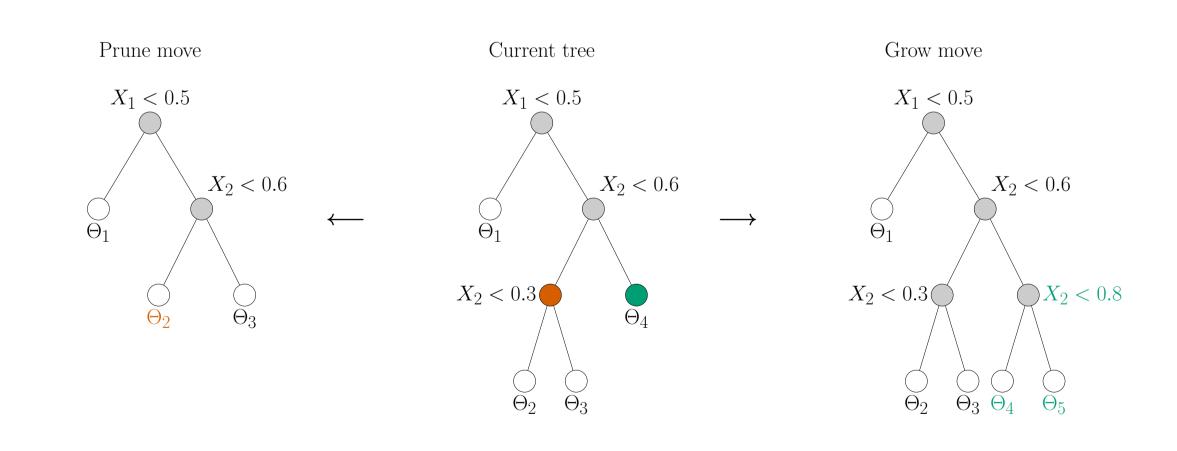
Note: setting $h(x) = \sqrt{2}\cos(x)$ leads to random Fourier feature-inspired approximation of treed Gaussian process ensembles.

Sampling

BART utilizes a Metropolis-within-Gibbs sampling scheme to sequentially update trees in the ensemble [1].

Step 1: Update $(\mathcal{T},\Theta) \to (\mathcal{T}^*,\Theta^*)$ with Metropolis-Hastings.

A new tree is proposed that differs from the current tree in exactly one node by considering either a *GROW* or *PRUNE* move:



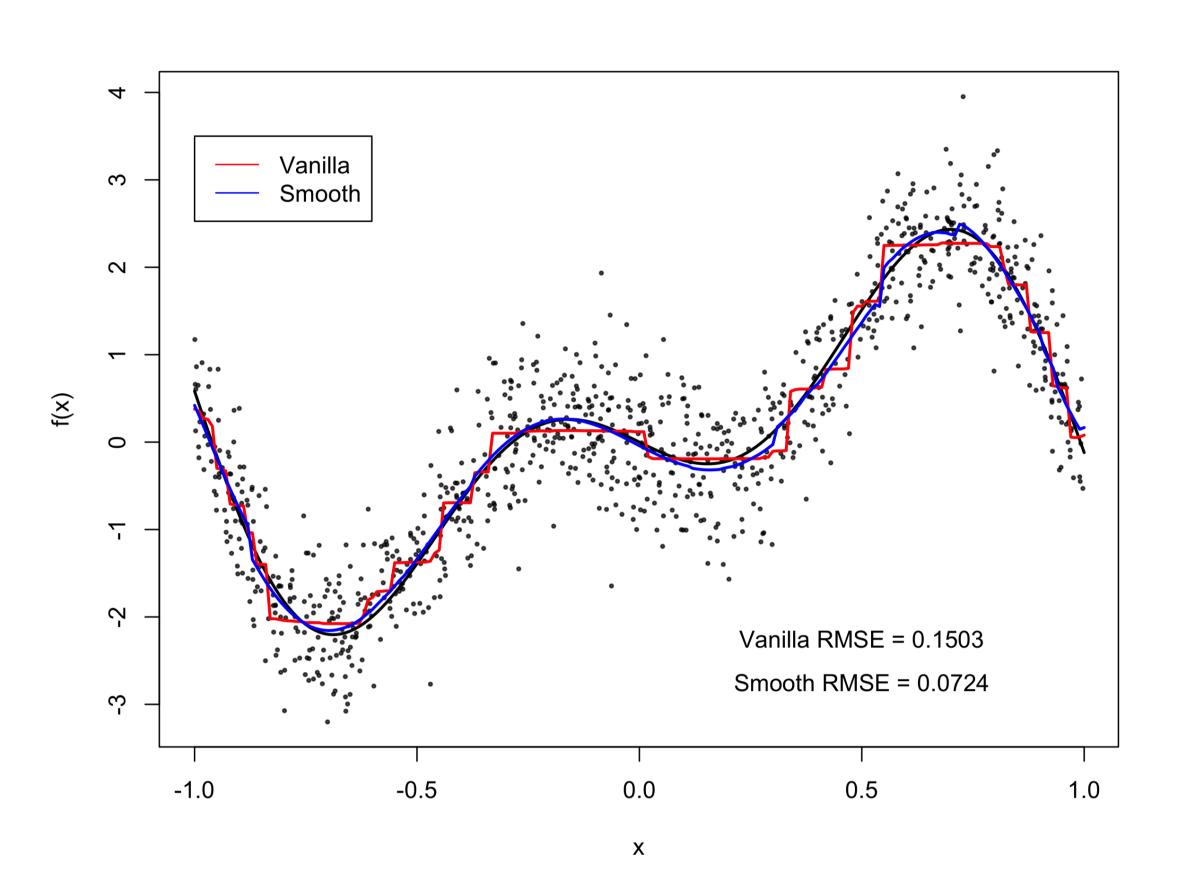
Move to the proposed tree based on a Metropolis-Hastings acceptance probability:

$$\alpha(\mathcal{T},\Theta \to \mathcal{T}^*,\Theta^*) = \underbrace{\frac{q(\mathcal{T},\Theta;\mathcal{T}^*,\Theta^*)}{q(\mathcal{T}^*,\Theta^*;\mathcal{T},\Theta)}}_{\text{transition ratio}} \times \underbrace{\frac{p(\mathbf{R} \mid \mathcal{T}^*,\Theta^*,\sigma^2)}{p(\mathbf{R} \mid \mathcal{T},\Theta,\sigma^2)}}_{\text{likelihood ratio}} \times \underbrace{\frac{p(\mathcal{T}^*,\Theta^*)}{p(\mathcal{T},\Theta)}}_{\text{prior ratio}}$$

Step 2: Update $\boldsymbol{\beta}^*|\mathbf{R}, (\mathcal{T}^*, \Theta^*) \sim \mathcal{N}_D$

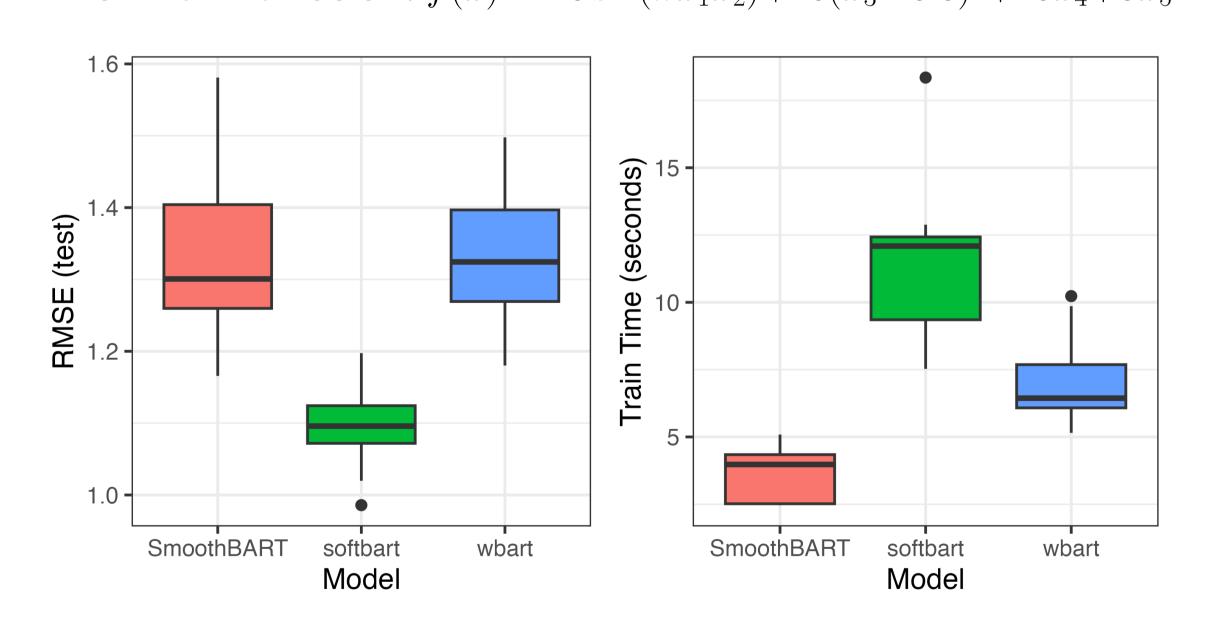
Note: updates only require a *linear* scan of the data

Vanilla vs. Smooth BART



Preliminary Empirical Results

Friedman Function: $f(x) = 10\sin(\pi x_1 x_2) + 20(x_3 - 0.5)^2 + 10x_4 + 5x_5$



References

- [1] Hugh A. Chipman, Edward I. George, and Robert E. McCulloch. BART: Bayesian Additive Regression Trees. In *The Annals of Applied Statistics*. 2010.
- [2] Ali Rahimi and Benjamin Recht.
 Random Features for Large-Scale Kernel Machines.
 In Advances in Neural Information Processing Systems. 2007.